Analyzing the Impact of Heterogeneous Blocks on FPGA Placement Quality

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Abstract—In this paper we propose a quantitative approach to analyze the impact of heterogeneous blocks (H-blocks) on the FPGA placement quality. The basic idea is to construct synthetic heterogeneous placement benchmarks with known optimal wirelength to facilitate the quantitative analysis. To the best of our knowledge, this is the first work that enables the construction of wirelength-optimal heterogeneous placement examples. Besides analyzing the quality of existing placers, we further decompose the impacts of H-blocks from the architectural aspect and netlist aspect. Our analysis shows that a heterogeneous design hides the wirelength degradation by a more compact netlist than its homogeneous version; however, the heterogeneity results in an optimality gap of 52% in wirelength, where 25% is from architectural heterogeneity and 27% is from netlist heterogeneity. Therefore, new heterogeneous placement algorithms are needed to bridge the optimality gap and improve design quality.

I. INTRODUCTION

Modern heterogeneous FPGA architecture contains not only configurable logic blocks (CLBs) but also heterogeneous blocks (H-blocks for short), such as: DSPs, BRAMs, etc. The introduction of H-blocks aims to improve performance and reduce area and power. Advanced FPGA synthesis algorithms are crucial for exploiting the heterogeneous resource efficiently, among which placement is an important stage to optimize the performance and power of on-chip interconnects.

The placement algorithm has been studied for decades. Basically, it can be divided into three classes: simulated annealing algorithm (e.g., VPR [1]), partition based algorithm (e.g., PPFF [2] and Michael et al. [3]), and analytical algorithm (e.g., HeAP [4] and Lin et al. [5]). More details of these algorithms can be found in [6] for FPGAs and [7] for ASICs. Despite the existence of well-developed placement algorithms, the appearance of H-blocks rise new problems. By far, existing placers only show their capability to handle H-blocks without discussing how their algorithms differ from the homogeneous case, such as VPR. Others do design different method with heterogeneity awareness. For example, HeAP adapts different rough legalization strategy for H-blocks. However, it is still unclear how well the placement algorithm handles the heterogeneity.

The heterogeneity mainly comes from two aspects: the architectural heterogeneity and the netlist heterogeneity. We observe that for the same homogeneous netlist without H-blocks, the wirelength quality of placement on homogeneous FPGAs differs from the quality of heterogeneous FPGAs. This impact is named architectural heterogeneity in this paper. Given the same heterogeneous FPGA, we can synthesize the RTL design into homogeneous netlist (without H-blocks) and heterogeneous netlist (with H-blocks), respectively. We observe that for a netlist with similar number of blocks, the wirelength quality of heterogeneous netlist differs from the quality of homogeneous netlists. This impact is named netlist heterogeneity in this paper. In the following analysis, we develop a systematic way to separately analyze the impact from architectural heterogeneity and netlist heterogeneity.

Our evaluation is based on the quantitative analysis: we first construct a synthetic netlist with known optimal wirelength. With such netlist, we further design experiments to quantify the impact from architectural heterogeneity and netlist heterogeneity respectively. We also evaluate the gap between existing placers, including VPR and Quartus, and the synthetic optimal placement. There are multiple previous works on synthetic benchmark generation. Chang et al. [8] firstly proposed the idea of generating placement benchmarks with known optimal wirelength (PEKO). However, the PEKO benchmarks are based on the assumption that all the blocks are of equal size and unique type, which is not suitable for heterogeneous FPGAs. Cong et al. [9] extended the PEKO idea to examine the optimality of mixed-size ASIC placers. However, H-blocks in FPGAs are different from macros in ASICs: macros in ASICs are freely movable, while H-blocks in FPGAs are only placeable in a limited set of tiles. Papa et al. [10] constructed benchmarks with structured optimal solutions that helped identify the issues of existing algorithms. Ward et al. [11] high-lighted the datapath placement problem, and constructed two customized designs that performed common logic functions with manual layouts. Again, all these existing placement benchmarks target ASIC placers but not FPGA placers.

In this paper, we make the following contributions:

- We quantify the impact of H-blocks on the wirelength quality of FPGA placement. Specifically, we can separately analyze such impact from two sources: architectural heterogeneity and netlist heterogeneity.
- To facilitate the analysis with synthetic heterogeneous benchmarks with known optimal wirelength, we propose an effective one-dimensional search method to generate...
such heterogeneous netlists.

- We evaluate and analyze the heterogeneous placement quality, in terms of optimality gap, on popular academic and industrial FPGA placers.
- Our synthetic benchmarks for heterogeneous FPGA placement will be released in the public domain\(^1\), available in VPR format, Altera VQM format [12], and probably in EDIF format with optimal placement information. Thus, researchers and developers of heterogeneous FPGA placers will be able to better understand the quality of their placers in handling the architectural heterogeneity and netlist heterogeneity separately.

The remainder of this paper is organized as follows. Section II qualitatively analyzes the complexity and inefficiency of the placement algorithm caused by the H-blocks. Before quantifying the impact of heterogeneity, Section III firstly introduces how to generate a synthetic netlist with known optimal wirelength with our one-dimensional search method. Section IV designs experiments to separately analyze the architectural heterogeneity and the netlist heterogeneity. Experimental study reported in Section V shows that there is still much room left for the improvement of heterogeneous FPGA placement. Finally, Section VI gives conclusions and future work.

II. Motivations

Based on our observations, the existence of H-blocks benefits the design by reducing the netlist size on one hand, and makes the placement more complicated on the other hand. Such observations motivate us to quantify the impact of H-blocks on the FPGA placement quality.

A. The Hidden Impact due to the Reduced Netlist Size

The H-blocks implement their own functionality in a more efficient way than CLBs, in terms of delay, area and power. By synthesizing such functionality into H-blocks, the whole design is benefit from performance improvement and area reduction.

For designs with identical functionality, mapping to a heterogeneous architecture will result in a more compact netlist. The statistics in Table II will show that both the number of logic blocks and the number of nets can reduce by about 30\% compared with its homogeneous implementation. Details for such heterogeneous and homogeneous synthesis flows will be described in Section IV.

B. Intuitions of the Difficulties in Heterogeneous Placement

The heterogeneity that complicates the placement problem mainly comes from two aspects: architectural heterogeneity and netlist heterogeneity.

The architectural heterogeneity restricts the legal locations of blocks to their specific tiles. As shown in Figure 1, in the heterogeneous island-style FPGA, different logic resources are aligned in tiles on the discrete, fixed locations. For a legal placement, one type of blocks in the netlist can only be put in the tiles with a corresponding type; tiles with different types serve as obstacle during placement. Thus, the heterogeneous tiles make the placement much more complicated compared with the placement with homogeneous tiles only.

Given the heterogeneous architecture, a portion of logics in the design may map into H-blocks. Such netlist is a heterogeneous netlist, containing more than one type of blocks. The wirelength of heterogeneous net is affected by different types of blocks jointly, making the wirelength minimization more difficult. Such difficulty comes from netlist heterogeneity.

Take the simulated annealing-based (SA) placement algorithm as an example, we will discuss informally how architectural heterogeneity and netlist heterogeneity degrade placement quality.

Adopting Monte-Carlo-based sampling, SA optimizes wirelength by perturbing the locations of blocks with block movement or swapping. In order to avoid huge degradation on wirelength, block movement and swapping are restricted within a small region of \((2R_{\text{limit}} + 1) \cdot (2R_{\text{limit}} + 1)\) (shown in Figure 1), where \(R_{\text{limit}}\) is called the “range limit”. The acceptance ratio of block movement is related with both temperature and movement strategy. According to Lam et.al. [13], good annealing schedule should decrease the temperature as fast as possible while maintaining the acceptance ratio at 0.44. This results in \(R_{\text{limit}}\) being the size of the entire chip for the first part of the annealing, shrinking gradually during the middle stages of the annealing, and finally being 1 logic block at low temperatures [14].

Because of the architectural heterogeneity, the existence of H-blocks reduces the number of candidate locations for block movement or swapping within the range limit. As shown in Figure 1, the logic block has fewer candidate locations when there have different type of blocks within the range limit. Such situation is even more serious as the range limit shrinks, affecting the acceptance rate at a low temperature. The limited exploration space will definitely affect the effectiveness of the simulated annealing.

On the other hand, the wirelength minimization for a heterogeneous net is more difficult than a homogeneous net. For example, in Figure 1 the movement distances for DSPs are larger than CLBs, resulting in higher probability of wirelength degradation, and thus lower probability of acceptance.

\(\text{Fig. 1. Island-style heterogeneous FPGA and different range limits for block movement from } Site_i.\)

\(^1\)Please download the synthetic benchmarks from https://github.com/FPGAStudy/placement/
III. SYNTHETIC BENCHMARK GENERATION

In Section II, we qualitatively analyze the issues that the heterogeneity brings in. However, quantitative analysis is still required to determine the necessity of heterogeneity-aware placement algorithm. Before quantifying the optimality gap of wirelength, we will firstly describe how to generate our synthetic benchmarks with known optimal wirelength.

A. Basic Idea

Since the placement problem is NP-hard, it is impractical to produce an optimal placement with minimum wirelength for a realistic design in reasonable time. Instead of obtaining an optimal placement of a realistic design for analysis, we generate synthetic benchmarks that reserve some properties from realistic designs while providing known optimal wirelength by construction. Common netlist properties for reference include the number of nets and the number of type-wise pins in each net.

For example, given the extracted netlist properties from a realistic design (e.g., there are one homogeneous net net1 and one heterogeneous net net2 in Figure 2(a)) and the target architecture (in Figure 2(b)), we want to construct a netlist with known optimal wirelength while preserving these properties.

![](Image)

**Fig. 2.** Toy benchmark generation.

The netlist generation is done by implementing each net one by one. A net with optimal wirelength can be constructed by connecting blocks within one of its optimal rectangles (defined latter). In Section III-B, We propose the one-dimensional search method to obtain the optimal rectangles for a given heterogeneous net. Please note that in terms of wirelength, each net might have multiple optimal rectangles located at different tiles. These optimal rectangles are candidates for net implementation with the minimum half-perimeter wirelength (HPWL). For example in Figure 2(b), Opt.Rect.1 and Opt.Rect.2 are optimal rectangles for net1 with a minimum HPWL of 4, assuming the pins are located at the center of blocks; and Opt.Rect.3 and Opt.Rect.4 are optimal rectangles for net2 with a minimum HPWL of 4. Then the choice of net candidates is done with the strategy depicted in Section III-C. For example, one possible netlist implementation consisting of net1 and net2 is shown in Figure 2(c).

B. Generate Optimal Rectangles for a Heterogeneous Net

The optimal wirelength of a synthetic net is guaranteed by construction. In the homogeneous case, the wirelength lower bound for a net with degree $p$ is quite easy to estimate [8]. If a net with $p$ pins achieves the lower bound, all the pins are accommodated in their optimal rectangle with a size of:

$$\left\lceil \sqrt{p} \right\rceil \cdot \left\lceil \frac{p}{\sqrt{p}} \right\rceil$$

The optimal rectangle for a net $n$ is defined as a rectangle with minimum half perimeter that can accommodate all types of blocks in net $n$. Thus, the minimum HPWL of net $n$ is calculated by the half-perimeter of the optimal rectangles enclosing its pins. Formally speaking, we represent an optimal rectangle with a 4-tuple $(x, y, l_x, l_y)$, where $(x, y)$ is the bottom-left corner (also called the starting point in the following) and $l_x$ (or $l_y$) is the width (or height) of the optimal rectangle. Each net might have multiple optimal rectangles, which are the candidates for synthetic net implementation. The choice of candidates will be discussed in Section III-C.

However, for heterogeneous nets, different types of blocks have different geometric size and align in different tiles. There seems no simple expression like Equation 1 to determine the optimal rectangle for a heterogeneous net, since the optimal size is related with locations. With the example in Figure 3, rectangles with different starting points have different size to accommodate the logic blocks. The optimal rectangle must be the minimum one starting from arbitrary locations. Thus, it is difficult to determine the optimal size with a simple expression like Equation 1.

To solve this problem, we propose an effective one-dimensional search method to find the optimal rectangles for the heterogeneous net $n$. Firstly we solve a simpler problem by focusing on the rectangles with the same starting point $s_i$, and search among these rectangles for the ones with minimum perimeter to accommodate all types of blocks in the net $n$. Then we use the above solver to search among all possible tiles as the starting point to obtain the globally optimal rectangles. Please note that not all the tiles on the chip should be searched and compared. Only those effective tiles are necessary to be searched. The criteria of effective tile will be defined latter.

The basic idea of the one-dimensional search method is to enumerate the width or height of rectangle only instead of both dimensions (width and height). For example, if $l_x$ is given, it is straightforward to compute the corresponding minimum $l_y$. After each enumeration of $l_x$, we can update the best-known smallest value of $l_x + l_y$, and keep incrementing $l_x$ for the next enumeration until the new $l_x$ is larger than the best-known smallest $l_x + l_y$. The search range for the $l_x$ is called the reasonable $l_x$.

Take net2 in Figure 2(a) as an example, we illustrate the process of one-dimensional search in Figure 3. Given the starting point $s_i$ or $s_j$, we want to find the rectangle with minimum half perimeter to accommodate net2. Let $l_x$ be the searching dimension, Table I shows the size of rectangles as...
The sequence of net implementation is determined by the netlist properties. Since optimal rectanges have the minimum half perimeter where \( i_x \geq 6 \) when starting at \( S_i \) and 6 when starting at \( S_j \). Compared with all the rectangles, the minimum half perimeter is 6 when taking \( S_j \) as the starting point. There are three optimal rectangles for net2, which are \((x_j, y_j, 2, 4)\), \((x_j, y_j, 3, 3)\), and \((x_j, y_j, 4, 2)\).

The pseudo code of the one-dimensional search algorithm is also shown in Algorithm 1.

**Algorithm 1** Find the optimal rectangles for a heterogeneous net

**Require:**
1) a heterogeneous FPGA
2) the number of type-wise blocks in the net \( e \) (labeled with \( d(e, *) \))

**Algorithm:**
1: \( HPWL_{OPT} = +\infty \)
2: \( \text{OptRects} := \emptyset \)
3: for each effective \( S_i \) do
4: \((x_i, y_i) := \) the coordinate of \( S_i \)
5: for each reasonable \( l_x \) do
6: calculate the minimum \( l_y \) such that in the rectangle 
\((x_i, y_i) - (x_i + l_x, y_i + l_y)\), the number of blocks of type \( t \) is not less than \( d(e, t) \)
7: if \( l_x + l_y < HPWL_{OPT} \) then
8: \( HPWL_{OPT} := l_x + l_y \)
9: \( \text{OptRects} := (x_i, y_i, l_x, l_y) \)
10: else if \( l_x + l_y = HPWL_{OPT} \) then
11: \( \text{OptRects} := \text{OptRects} \cup (x_i, y_i, l_x, l_y) \)
12: end if
13: end for
14: end for
15: return \( \text{OptRects} \)

Since optimal rectangles have the minimum half-perimeter compared with other rectangles starting at arbital tiles, each net implemented within its optimal rectangle must have minimum HPWL. However, in practice, we do not need to explore all the tiles over the FPGA chip, since modern FPGAs have column-based structures, and the columns usually have repeated patterns. We can find a minimum set of tiles that can represent all the tiles on chip. Such set of tiles is called the effective tiles. Obviously, exploring within the effective tiles can still guarantee the optimality. In practice, the number of effective tiles can be quite small. Take VPR architecture as an example, the heterogeneous architecture (defined in the XML file) will tell the starting point of the type-wise tiles and the intervals. Thus, the tiles within the intervals can represent the periodical appearance of other tiles. For example, the effective tiles for the architecture in the Figure 3 have only 2 DSPs (labeled 7,8) and 6 CLBs (labeled 1~6). With the effective tiles, the searching space can be greatly reduced.

### C. Generate a Heterogeneous Netlist with Known Optimal Wirelength

Netlist is generated with the flow in Figure 4. The net set \( N_i \) containing netlist properties is extracted from realistic designs. We construct each net \( N_i \) in set \( N \) until it is empty. The sequence of net implementation is determined by the number of optimal rectangles each net has. Basically, the heterogeneous net containing rare resources (e.g., DSPs, IOs) tends to have fewer candidates than the homogeneous net with only CLBs. A high-degree net is likely to have fewer optimal rectangles than a low-degree net. In our implementation, Net with fewer optimal rectangles will be generated first.

With Algorithm 1, we can find the optimal rectangles for a given net \( N_i \). In terms of net implementation candidate, we simply choose the bottom-left-most \( R_i \) first. If the input or output pins of the blocks in \( R_i \) are used up, we choose another optimal rectangle \( R_j \). If the net cannot find an optimal rectangle with enough available pin resources, such net will be thrown away instead of finding a sub-optimal implementation. The netlist can be constructed when all the nets have been processed.

Please note that the final netlist properties might be different from the properties extracted from realistic designs. Since for each tile, the physical pin number is limited. What’s more, if the heterogeneity is quite complex, the optimal wirelength can only obtained at a few number of tiles, making those tiles become hot spots. Thus, the latter arrived net will be difficult to find its accommodation because of the exhaust of pin resources. In this way, our benchmark generation is in a “best-effort” style.

### D. Time Complexity Analysis

A pessimistic estimation for the number of reasonable \( l_x \) to be searched at one starting tile is \( kT \), where \( k \) is the net degree and \( T \) is the number of block types in the net. The optimal rectangles can be achieved by searching tiles in the effective tiles. Supposing the effective tiles lie within the range of \( T_x T_y \).
The searching time spends on one net equals to $T_x T_y k T$. The overall pessimistic estimation of the runtime is $O(T_x T_y k T N)$, where $N$ is the number of nets.

In practice, the runtime can be much smaller than this estimation, and it is possible to speed up the benchmark generation by building a lookup table of optimal rectangles for a specific FPGA architecture.

IV. EXPERIMENTAL FLOW FOR THE QUANTITATIVE ANALYSIS

In this section we describe the evaluation flow to quantify wirelength gaps of state-of-the-art placers, including VPR and Quartus. And we further design experiments to separately analyze the impacts of architectural heterogeneity and netlist heterogeneity.

A. Evaluation Flow

There are multiple choices for FPGA synthesis: 1) synthesize the RTL design into a homogeneous netlist and map on a homogeneous FPGA; 2) synthesize the RTL design into a homogeneous netlist and map on a heterogeneous FPGA; 3) synthesize the RTL design into a heterogeneous netlist and map on a heterogeneous FPGA. In this section, we depict the evaluation flow to calculate wirelength gaps of these three different choices on the academic placer VPR and the industrial placer Quartus.

As shown in Figure 5, the evaluation flow takes an RTL design as input and output the wirelength gap of VPR placer or Quartus placer. The whole flow consists of three steps: 1) synthesize the RTL design into a homogeneous or heterogeneous netlist (as a reference netlist) with front-end synthesis flow; 2) given the reference netlist and the target architecture, we use the Algorithm 1 in Section III to generate a synthetic benchmark with known optimal wirelength; 3) feed VPR placer and Quartus placer with the synthetic benchmark and obtain the wirelength gap towards optimal placement solution.

We have customized the setting files of synthesis tools to eliminate the nosing impacts from these following parts:

- Different optimization efforts of front-end synthesis tools: ODIN and Quartus. We use ODIN and Quartus to parse RTL designs into BLIF format targeting heterogeneous VPR architecture and homogeneous VPR architecture respectively. The BLIF files are generated without optimization, so that ODIN and Quartus in the front end only serve as RTL parsers. For example, we turn on the option of “dump blif before optimization” in Quartus verilog parsing. The optimization of BLIF netlist is then left to ABC.

- Placers pay much efforts to optimize critical paths. For both VPR placer and Quartus placer, we specify the “wirelength-driven” placement mode. For example, in VPR, we set the placement to be “bounding-box driven placement”. And in Quartus, we turn off the timing optimization with setting “optimize timing off”.

- Quartus placer does not only placement but also packing. The synthetic netlist (in VQM format) generated is the LAB-level netlist. In order to prevent the packer from disturbing the packing at the BLE-level, we use the feature of “virtual pin” and “logic lock” to lock the BLE blocks within the same “LAB”.

Based on different netlist type and architecture type, our evaluation flow can be classified into three flows:

- **Flow-A**: generate a **homogeneous** netlist with known optimal wirelength targeting a **homogeneous** architecture.
- **Flow-B**: generate a **homogeneous** netlist with known optimal wirelength targeting a **heterogeneous** architecture.

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3We use Quartus 12.0 and Cyclone II FPGA device.

4We use VPR-5.0 placer because the placement algorithms in VPR-5.0 and VPR-7.0 do not have significant changes. The architecture we used is defined in “K4-n12.xml”.

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Fig. 4. Netlist generation flow

Fig. 5. The synthesis flow: (a) homogeneous flow (b) heterogeneous flow
• Flow-C: generate a heterogeneous netlist with known optimal wirelength targeting a heterogeneous architecture.

Please note that the netlist topology may be different for Flow-A and Flow-B even with the same reference netlist, since the optimal rectangles are different for different architectures. These three flows will be used to evaluate the placement quality of VPR placer and Quartus placer in Section V-A.

B. Separate the Impacts of Architectural and Netlist Heterogeneity

For the sake of quantifying the impacts of architectural and netlist heterogeneity, a direct comparison of performance using the synthetic benchmarks generated with Flow-A, Flow-B, and Flow-C cannot work due to the difference of netlist topology. In order to remove the impact of netlist topology, we design three cases to separate the impact of architecture’s heterogeneity from the netlist heterogeneity.

• Case-1: Given the reference netlist, we will use Flow-A to generate the synthetic netlist with known optimal wirelength targeting the homogeneous architecture.

• Case-2: By adding some heterogeneous tiles, we expand the homogeneous architecture into a heterogeneous architecture, while keeping the netlist unchanged. With some simple computation, we can get an upper-bound of the optimal wirelength for Case-2.

• Case-3: Based on Case-2, some H-blocks blocks will be added into the homogeneous netlist to generate the heterogeneous netlist. Similar to Case-2, we can also get a upper-bound of the optimal wirelength for Case-3.

By comparing the placement results in Case-1 and Case-2, we can get the amount of impact from architecture heterogeneity. While comparing the placement results of Case-2 and Case-3, we can quantify the impact from netlist heterogeneity on wirelength.

Using the example depicted in the Figure 6, we further explain the details. In the Figure 6(a), we have generated the homogeneous netlist with known optimal wirelength with Flow-A, which containing a 2-degree net (net1), a 9-degree net (net2), and a 4-degree net (net3). The total optimal wirelength is 7.

Then the heterogeneous tiles (e.g., DSPs) will be inserted into the homogeneous architecture, as shown in Figure 6 (b). The number of tiles to be added and where to insert those tiles are directed by the real heterogeneous FPGA architecture. For example, in the heterogeneous VPR architecture, the starting point of the heterogeneous tiles and the interval for periodical appearance are defined in the architecture file. After transforming the homogeneous architecture into the heterogeneous architecture, we will calculate the wirelength for the stretched placement after heterogeneous tile insertion, which is an upper-bound of the optimal wirelength. As shown in Figure 6(b), nets spanning the heterogeneous sites are no longer optimal (i.e. net1 and net2 are no longer optimal). So 9 is a upper-bound of the optimal wirelength.

Then we will add some H-blocks into the netlist to transform it into a heterogeneous netlist. Please note that we only add H-blocks for those nets, whose wirelength will not be increased after adding these H-blocks. For example, in Figure 6(c) we only add H-blocks for net2. Thus, with such constraint, the upper-bound for the optimal wirelength in Figure 6(c) is same with wirelength for Figure 6(b). The wirelength upper-bound is still 9.

With the netlists generated according to these three cases, we can perform comparisons to separately quantify the impacts of architectural heterogeneity and netlist heterogeneity. The statistics will be shown in Section V-B.

V. EXPERIMENTAL RESULTS AND DISCUSSIONS

Our synthetic benchmark generator is implemented in C++ and compiled with G++ 4.5.1. The generator runs on Intel Xeon CPU E5620 Linux work station. Realistic RTL designs for reference are either from the VPR benchmark suite or from the QUIP benchmark suite. In order to test the scalability, we also implement two large designs (fft and ifft) in verilog.

With the flow shown in Figure 5, we synthesize the realistic RTL designs into the reference netlists. Properties of reference netlists are depicted in Table II, including the number of nets (#Net) and the number of blocks (#CLB, #DSP, #LAB).

The synthetic netlists will reserve the features of these realistic benchmarks at the best effort. By comparing the number of net (Diff1) and the number of CLB (Diff2) of homogeneous netlist and heterogeneous netlist, we can see that for the same design, synthesizing into a heterogeneous netlist can save around 30% resource utilization compared to a homogeneous netlist.

The name of synthetic netlist generated by referring the specific realistic design is listed in the column of “Syn.name” in Table II, which will be used in the following experiments. Please note that both Bench.aX and Bench.bX are homogeneous netlists generated from the same realistic designs. However, they are targeting different architectures, homogeneous architecture and heterogeneous architecture respectively. Thus, both the optimal wirelength and netlist topology are different.
A. Evaluating the Quality of Existing Placers

With evaluation flows (Flow-A, Flow-B, and Flow-C) in Section IV-A, we have quantified the quality of VPR placer and Quartus placer on wirelength. The wirelength gap (WG) is defined in Equation 2, where WL_{realistic} is the HPWL after VPR placement or Quartus placement and WL_{optimal/upperbound} is the optimal or upper-bound wirelength for our synthetic benchmarks.

\[
WG = \frac{WL_{realistic} - WL_{optimal/upperbound}}{WL_{optimal/upperbound}} \quad (2)
\]

The placement quality of VPR is evaluated with synthetic benchmarks generated by Flow-A, Flow-B, and Flow-C respectively. WG for each condition is shown in Table III, where OPT_{wl} is the optimal wirelength and VPR_{wl} is the wirelength of VPR placer. Statistics show that:

- When placing homogeneous netlist on homogeneous architecture, WG is around 33%.
- When placing homogeneous netlist on heterogeneous architecture, WG is around 40%.
- When placing heterogeneous netlist on heterogeneous architecture, WG is 48% on average.
- The reduction around 30% problem size (in Table II) almost shows no advantage when compare the performance of Flow-B and Flow-C. The benefit of the problem size reduction is canceled out by the wirelength degradation caused by heterogeneity.

Thus, we call for efficient and effective heterogeneity-aware placer to eliminate the degradation of H-blocks.

For the Quartus placer, we have generated heterogeneous netlist with Flow-C targeting the Cyclone II FPGA device. Thus, we call for efficient and effective heterogeneity-aware placer to eliminate the degradation of H-blocks.

For the Quartus placer, we have generated heterogeneous netlist with Flow-C targeting the Cyclone II FPGA device. The notation of OPT_{wl}, Quartus_{wl}, and WG are optimal wirelength, wirelength reported by Quartus, and the wirelength gap respectively. Statistics in the Table IV show that there are around 116% wirelength gap on average.

### Table II

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### Table III

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<td>Bench.a9</td>
<td>88369</td>
<td>129705</td>
</tr>
<tr>
<td>Avg.</td>
<td>-</td>
<td>33%</td>
</tr>
</tbody>
</table>

### Table IV

<table>
<thead>
<tr>
<th>Reference Netlist Property</th>
<th>Design</th>
<th>#Net</th>
<th>#LAB</th>
<th>#DSP</th>
<th>Quartus_{wl}</th>
<th>OPT_{wl}</th>
<th>VPR_{wl}</th>
<th>WG</th>
</tr>
</thead>
<tbody>
<tr>
<td>nut_004</td>
<td>111</td>
<td>29</td>
<td>1</td>
<td>267</td>
<td>493</td>
<td>85%</td>
<td>1193</td>
<td>2561</td>
</tr>
<tr>
<td>nut_001</td>
<td>502</td>
<td>130</td>
<td>4</td>
<td>1852</td>
<td>4618</td>
<td>149%</td>
<td>1006</td>
<td>2051</td>
</tr>
<tr>
<td>flip_risc8</td>
<td>826</td>
<td>218</td>
<td>0</td>
<td>3360</td>
<td>5041</td>
<td>50%</td>
<td>3148</td>
<td>5227</td>
</tr>
<tr>
<td>mux8_128bit</td>
<td>624</td>
<td>112</td>
<td>0</td>
<td>3117</td>
<td>8213</td>
<td>163%</td>
<td>3609</td>
<td>9011</td>
</tr>
<tr>
<td>mac1</td>
<td>1352</td>
<td>411</td>
<td>0</td>
<td>3612</td>
<td>8128</td>
<td>125%</td>
<td>6948</td>
<td>17598</td>
</tr>
</tbody>
</table>

Aver. | 2270 | 1006 | 0    | 42   |
B. Quantify the Impacts from Heterogeneity

In order to further separate the impacts between architectural heterogeneity and netlist heterogeneity, we have generated the synthetic netlists corresponding to the Case-1, Case-2, and Case-3 in Section IV-B. For each synthetic netlist, we will give either the optimal wirelength or an upper bound. These synthetic netlists will feed in the VPR placer to get the placement wirelength.

The WG for three cases have been shown in Figure 7. Results show that:

- Architectural heterogeneity alone introduces at least an extra 25% of WG.
- Netlist heterogeneity by adding only a small number of DSPs (5.2% of the total number of blocks on average) can introduce additional 27% WG.

![Fig. 7. Quantify the heterogeneity’s impact on wirelength](image)

VI. CONCLUSION AND FUTURE WORK

To summarize, we construct synthetic benchmarks with known optimal placement, in terms of wirelength, with the presence of H-blocks. Specifically, we propose an efficient one-dimensional search method to generate a heterogeneous net with known optimal wirelength.

The benchmarking results of the academic FPGA placer VPR show that: (i) the average optimality gap is 9% to 93% for heterogeneous placement, compared with the average gap of 14% to 76% for homogeneous placement; (ii) the degradation of wirelength by H-blocks cancel out the benefit of problem size reduction; (iii) the heterogeneous architecture alone degrades the placement quality by over 25%; (iv) the heterogeneous netlist degrades the quality by another 27%.

One potential problem of such analysis is that the benchmarks are synthetic and may not represent the characteristics of the real-world designs. As a future work, we are going to explore possible metrics that can measure the “difficulty” of placement for a given netlist. If the synthetic benchmarks are easier to place than real-world designs, we have more confidence the gap analysis results are informative, because the gap that we obtain is smaller than the actual optimality gap. Otherwise, we have to resort to other methods to generate benchmarks with known optimal wirelength that are easier to place.

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